

Laplacian Basics

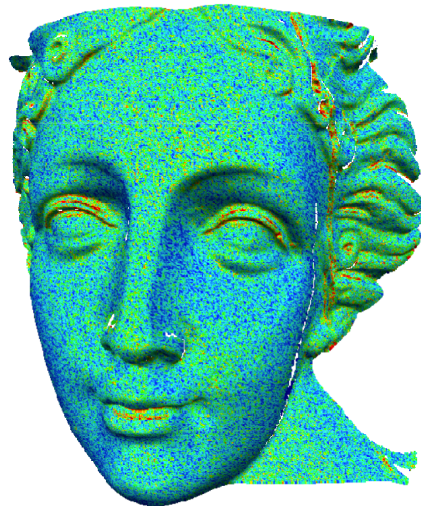
(Smoothing, Cotangent Laplacian)

Instructor: Hao Su

MESH SMOOTHING (AKA DENOISING, FILTERING, FAIRING)

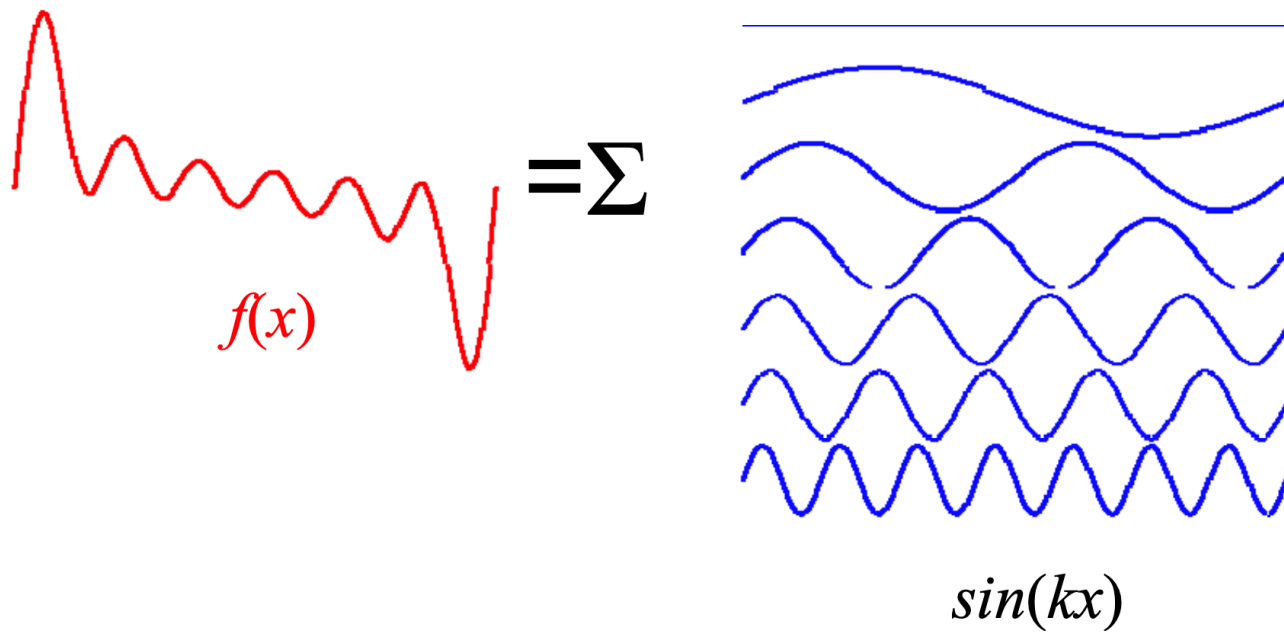
Mesh Smoothing

- Input: Noisy mesh (scanned or other)
- Output: Smooth mesh
- How: Filter out high frequency noise



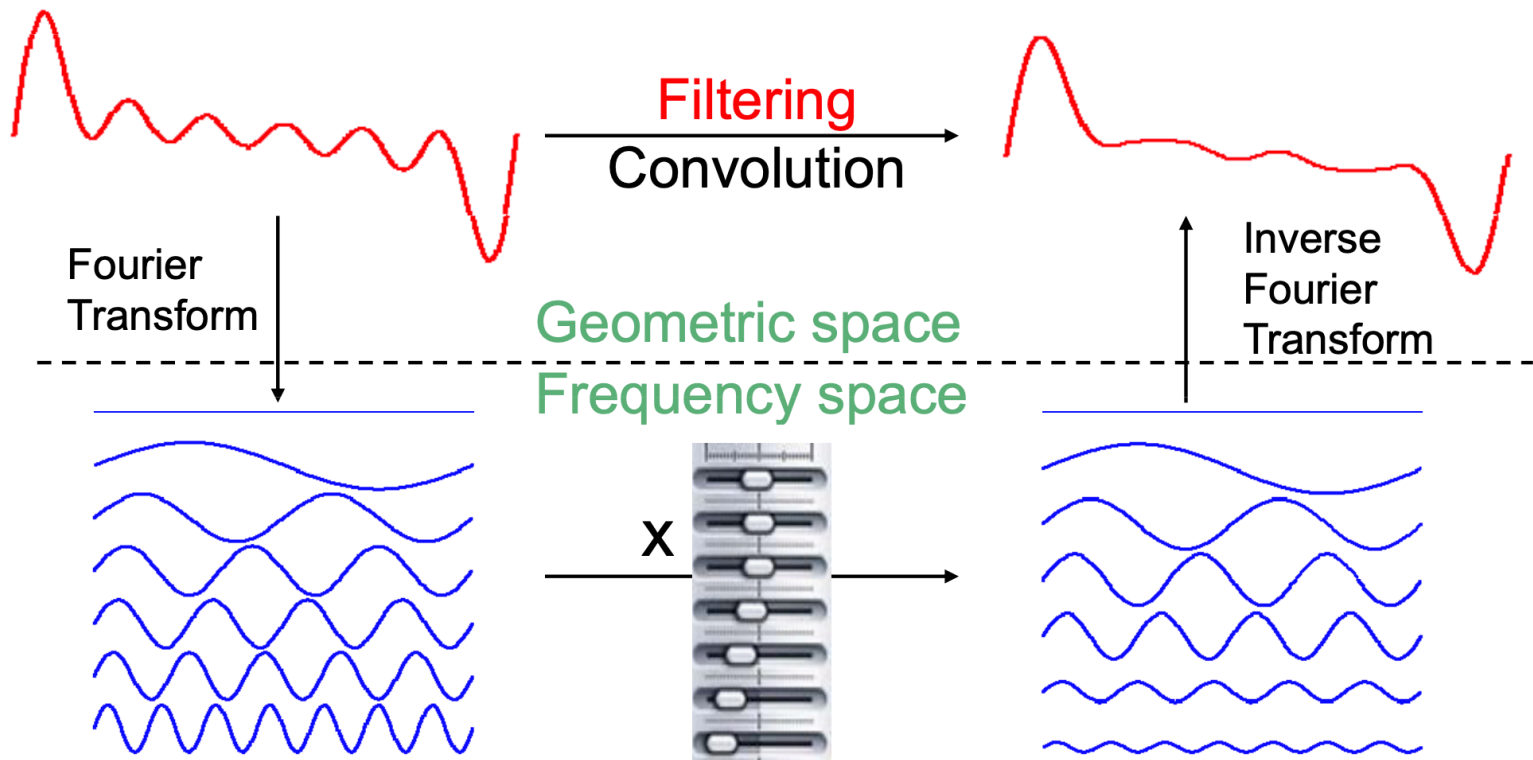
Smoothing by Filtering

Fourier Transform



Smoothing by Filtering

Fourier Transform



Filtering on a Mesh

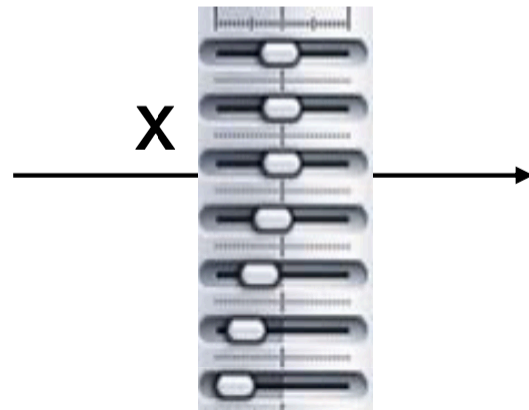


Filtering
[Taubin 95]



Geometric space
Frequency space

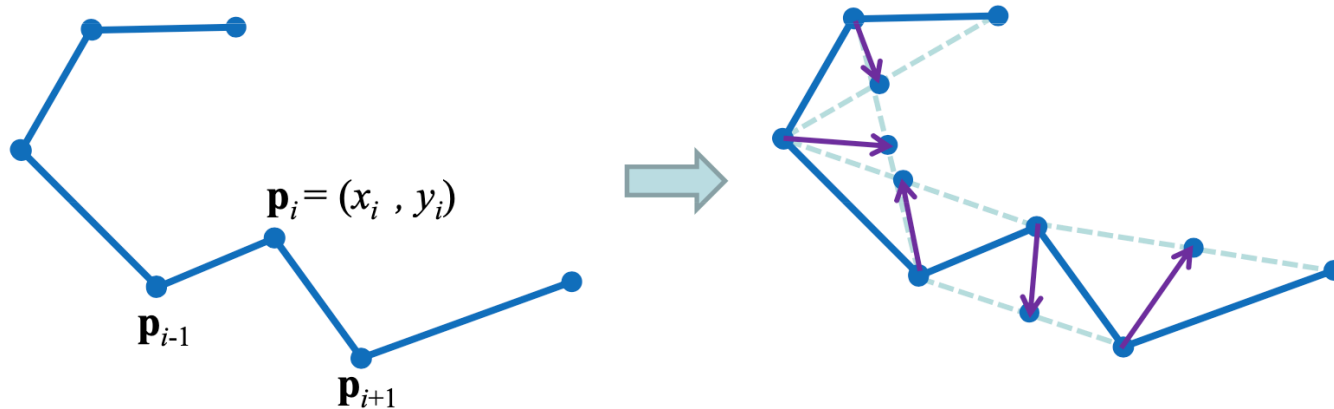
?



?

Laplacian Smoothing

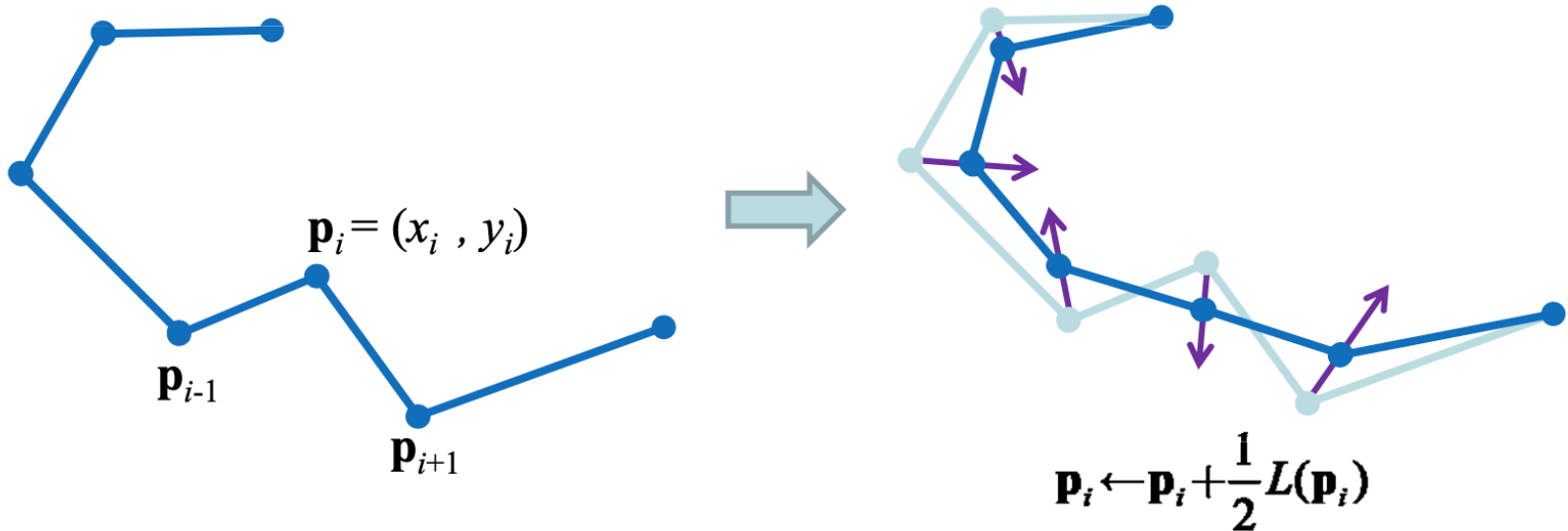
- An easier problem: How to smooth a curve?



$$L(\mathbf{p}_i) = \frac{1}{2}(\mathbf{p}_{i+1} - \mathbf{p}_i) + \frac{1}{2}(\mathbf{p}_{i-1} - \mathbf{p}_i)$$

Laplacian Smoothing

- An easier problem: How to smooth a curve?



Finite difference
discretization of second
derivative
= Laplace operator in
one dimension

$$L(\mathbf{p}_i) = \frac{1}{2}(\mathbf{p}_{i+1} - \mathbf{p}_i) + \frac{1}{2}(\mathbf{p}_{i-1} - \mathbf{p}_i)$$

Laplacian Smoothing

Algorithm:

Repeat for m iterations (for non boundary points):

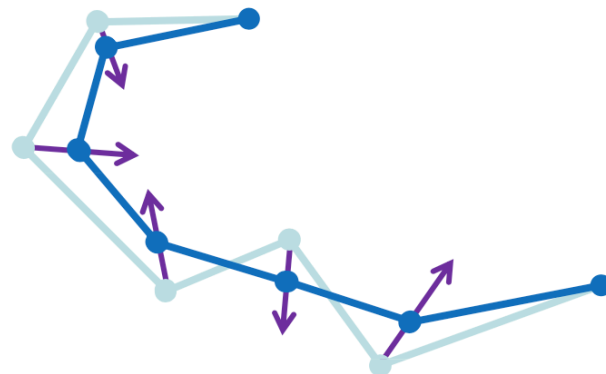
$$\mathbf{p}_i \leftarrow \mathbf{p}_i + \lambda L(\mathbf{p}_i)$$

For which λ ?

$$0 < \lambda < 1$$

Closed curve converges to?

Single point



Spectral Analysis

- Closed curve

$$\text{Re-write } \mathbf{p}_i^{(t+1)} = \mathbf{p}_i^{(t)} + \lambda L(\mathbf{p}_i^{(t)})$$

$$L(\mathbf{p}_i) = \frac{1}{2}(\mathbf{p}_{i+1} - \mathbf{p}_i) + \frac{1}{2}(\mathbf{p}_{i-1} - \mathbf{p}_i)$$

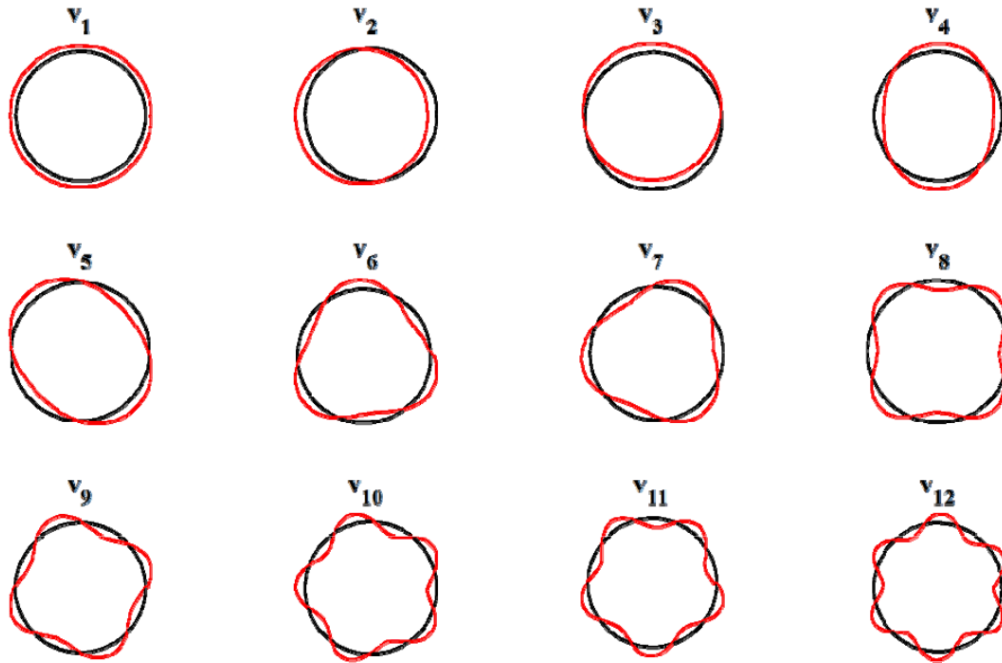
$$\text{in matrix notation: } \mathbf{P}^{(t+1)} = \mathbf{P}^{(t)} - \lambda \mathbf{L} \mathbf{P}^{(t)}$$

$$\mathbf{P} = \begin{pmatrix} x_1 & y_2 \\ \dots & \dots \\ x_n & y_n \end{pmatrix} \in \mathbb{R}^{n \times 2} \quad \mathbf{L} = \frac{1}{2} \begin{pmatrix} 2 & -1 & & & & & -1 \\ -1 & 2 & -1 & & & & \\ & & \dots & & & & \\ & & & -1 & 2 & -1 & \\ -1 & & & & -1 & 2 & \end{pmatrix} \in \mathbb{R}^{n \times n}$$

The Eigenvectors of L

$$\mathbf{L} = \mathbf{V} \mathbf{D} \mathbf{V}^T$$

$$\mathbf{V} = \begin{pmatrix} | & | & \dots & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \\ | & | & \dots & | \end{pmatrix}, \quad \mathbf{D} = \begin{pmatrix} k_1 & & & \\ & k_2 & & \\ & & \dots & \\ & & & k_n \end{pmatrix}$$



$$0 \leq \lambda(L) \leq 2$$

Lemma 5.3.1. *The Laplacian of R_n has eigenvectors*

$$\begin{aligned}\mathbf{x}_k(u) &= \cos(2\pi ku/n), \text{ and} \\ \mathbf{y}_k(u) &= \sin(2\pi ku/n),\end{aligned}$$

for $0 \leq k \leq n/2$, ignoring \mathbf{y}_0 which is the all-zero vector, and for even n ignoring $\mathbf{y}_{n/2}$ for the same reason. Eigenvectors \mathbf{x}_k and \mathbf{y}_k have eigenvalue $2 - 2\cos(2\pi k/n)$.

Spectral Analysis

Then: $\mathbf{P}^{(t+1)} = \mathbf{P}^{(t)} - \lambda \mathbf{L} \mathbf{P}^{(t)} = (\mathbf{I} - \lambda \mathbf{L}) \mathbf{P}^{(t)}$

After m iterations: $\mathbf{P}^{(m)} = (\mathbf{I} - \lambda \mathbf{L})^m \mathbf{P}^{(0)}$

Can be described using eigen-decomposition of \mathbf{L}

$\mathbf{L} = \mathbf{V} \mathbf{D} \mathbf{V}^T$

$\mathbf{V} = \begin{pmatrix} | & | & \dots & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \\ | & | & \dots & | \end{pmatrix}, \mathbf{D} = \begin{pmatrix} k_1 & & & \\ & k_2 & & \\ & & \dots & \\ & & & k_n \end{pmatrix}$

$\mathbf{P}^{(m)} = \mathbf{V} (\mathbf{I} - \lambda \mathbf{D})^m \mathbf{V}^T \mathbf{P}^{(0)}$

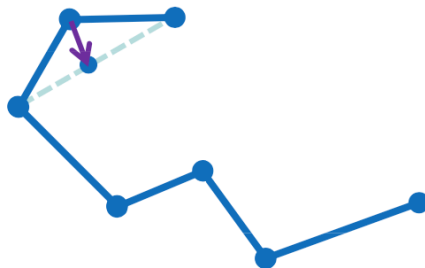
Filtering high frequencies

Laplacian Smoothing on Meshes

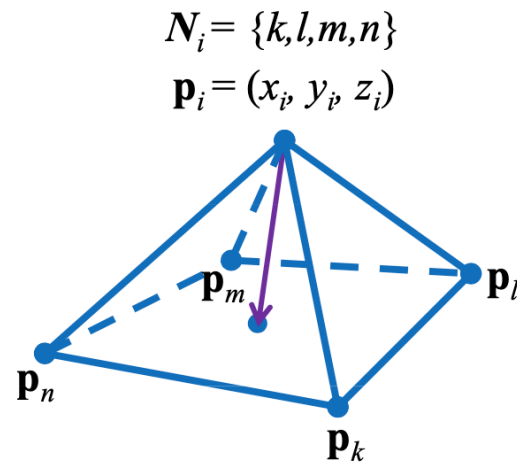
Same as for curves:

$$\mathbf{p}_i^{(t+1)} = \mathbf{p}_i^{(t)} + \lambda \Delta \mathbf{p}_i^{(t)}$$

What is $\Delta \mathbf{p}_i$?

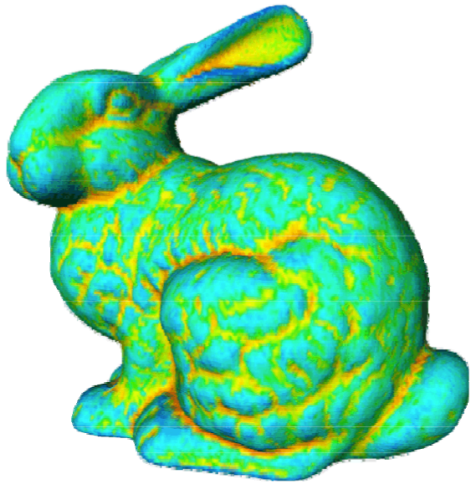


$$\frac{1}{2}(\mathbf{p}_{i+1} + \mathbf{p}_{i-1}) - \mathbf{p}_i$$

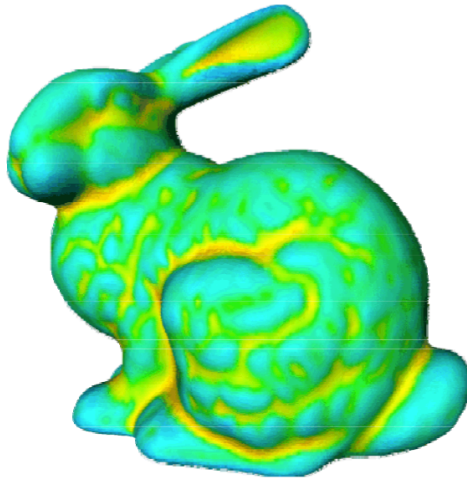


$$\frac{1}{|N_i|} \left(\sum_{j \in N_i} \mathbf{p}_j \right) - \mathbf{p}_i$$

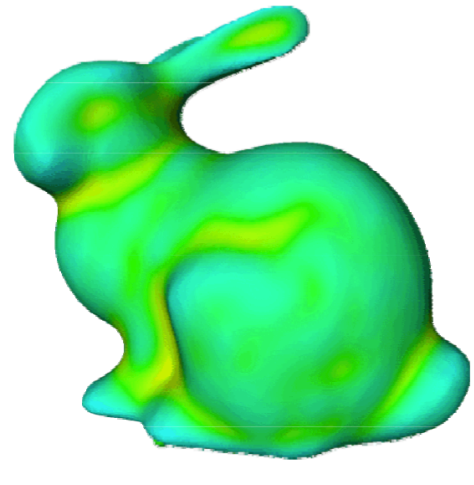
Laplacian Smoothing on Meshes



0 Iterations



5 Iterations



20 Iterations

Laplacian Smoothing

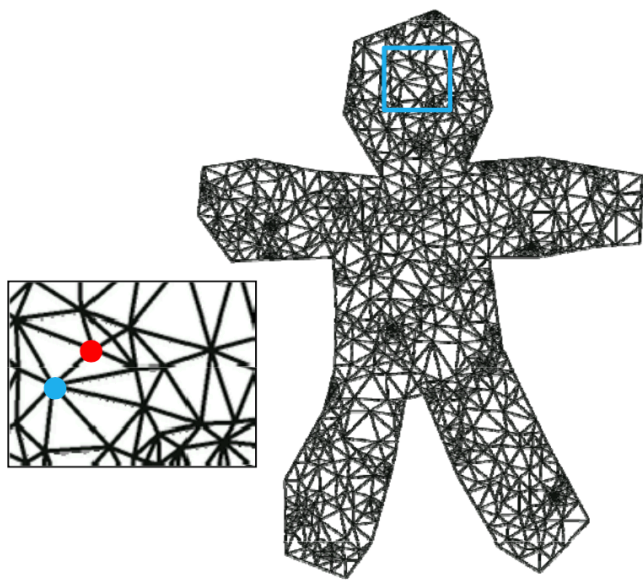
$$\mathbf{p}_i^{(t+1)} = \mathbf{p}_i^{(t)} + \lambda \Delta \mathbf{p}_i^{(t)}$$

$\Delta \mathbf{p}_i$ = mean curvature normal

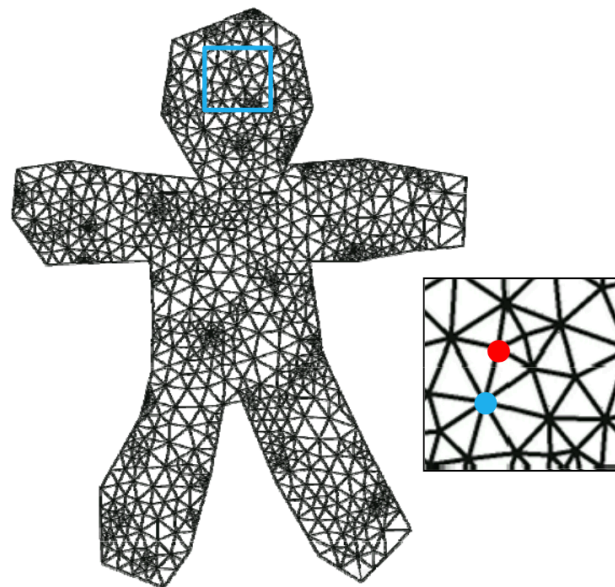
 mean curvature flow

Laplace Operator Discretization

- Sanity check — what should happen if the mesh lies in the plane: $p_i = (x_i, y_i, 0)$?



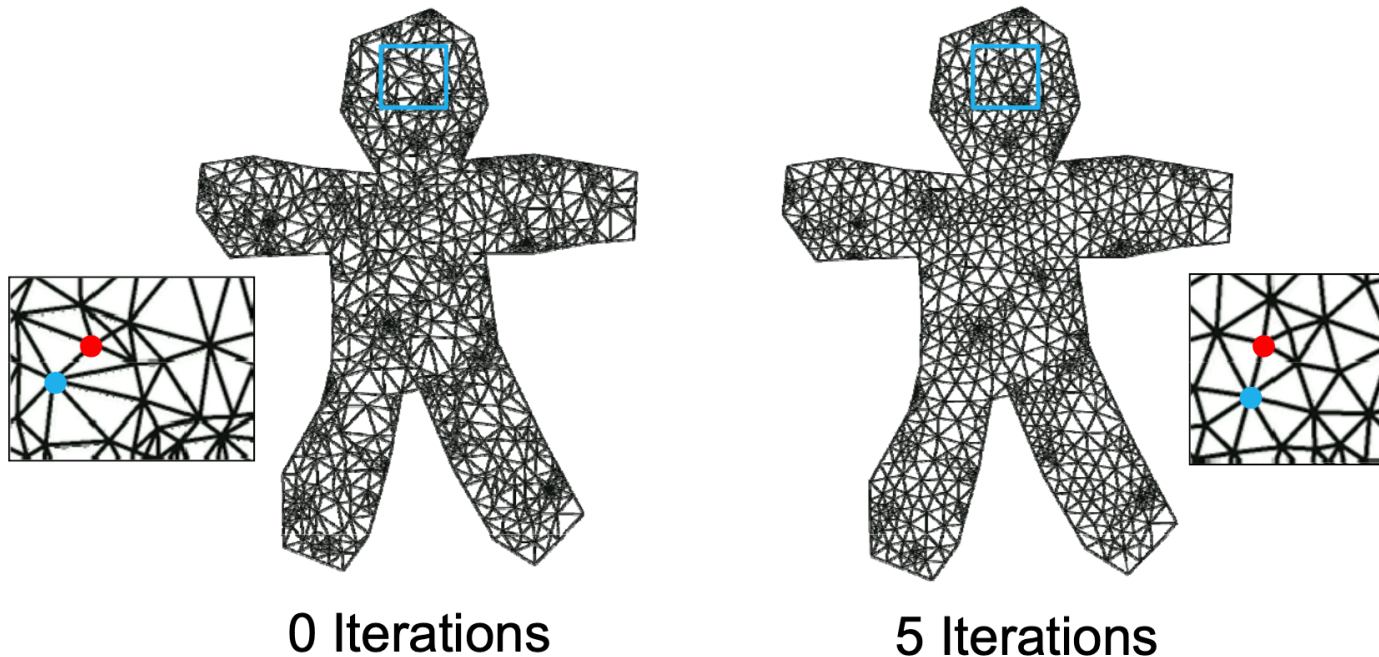
0 Iterations



5 Iterations

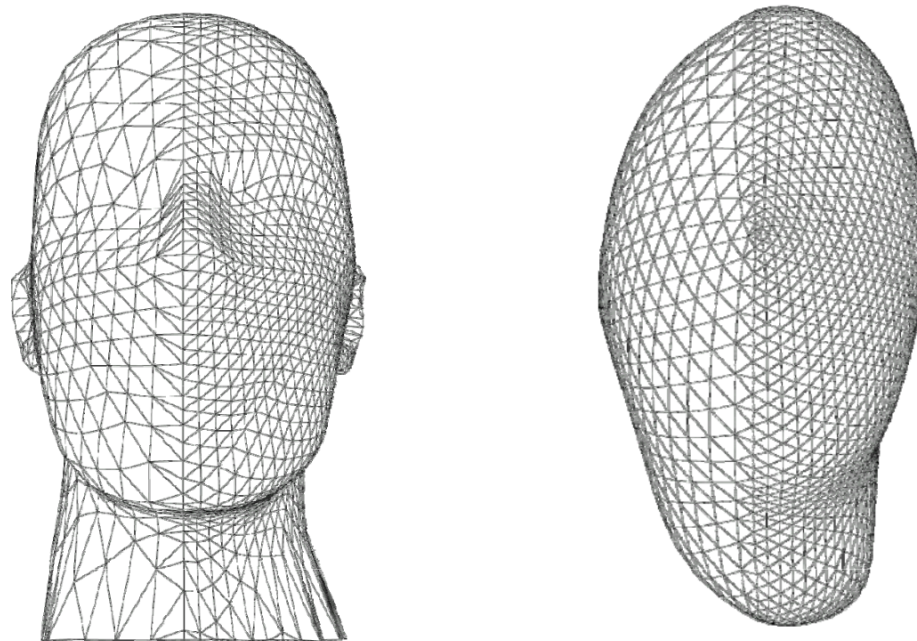
Laplace Operator Discretization

Not good – A flat mesh is smooth, should stay the same after smoothing



Laplace Operator Discretization

Not good – The result should not depend on triangle sizes



From Desbrun et al., Siggraph 1999

What Went Wrong?

Back to curves:

$$\frac{1}{2}(\mathbf{p}_{i+1} + \mathbf{p}_{i-1}) - \mathbf{p}_i$$



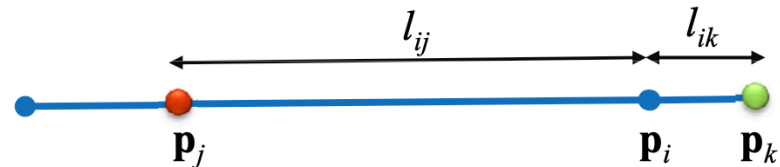
Same weight for both neighbors,
although one is closer

The Solution (1D)

Use a weighted average to define Δ

Which weights?

$$w_{ij} = \frac{1}{l_{ij}} \quad w_{ik} = \frac{1}{l_{ik}}$$

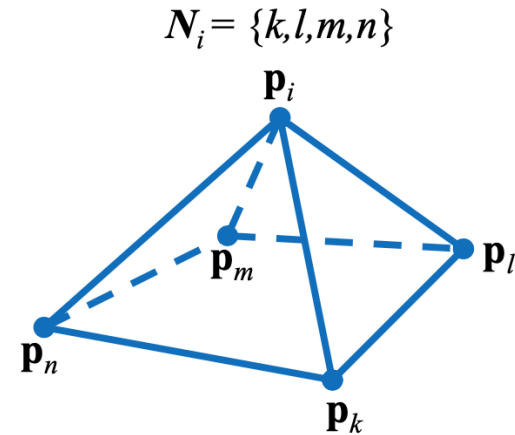
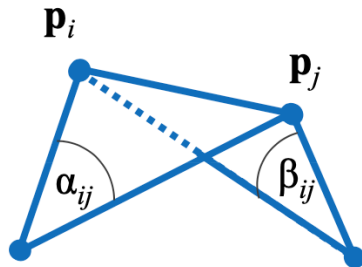


$$L(\mathbf{p}_i) = \frac{w_{ij}\mathbf{p}_j + w_{ik}\mathbf{p}_k}{w_{ij} + w_{ik}} - \mathbf{p}_i$$

Straight curves will be invariant to smoothing

Solution (2D)

Use a weighted average to define Δ
Which weights?

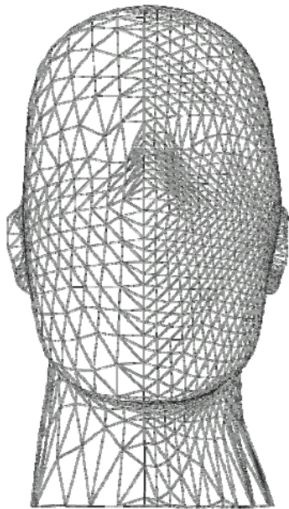


$$w_{ij} = \frac{h_{ij}^1 + h_{ij}^2}{l_{ij}} = \frac{1}{2} (\cot \alpha_{ij} + \cot \beta_{ij})$$

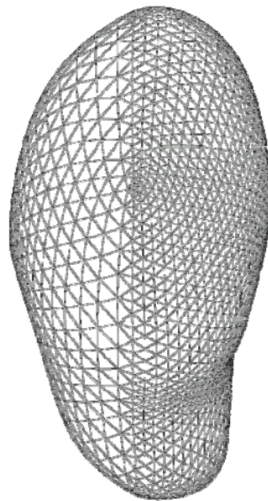
$$L(\mathbf{p}_i) = \frac{1}{\sum_{j \in N_i} w_{ij}} \left(\sum_{j \in N_i} w_{ij} \mathbf{p}_j \right) - \mathbf{p}_i$$

Planar meshes will be invariant to smoothing

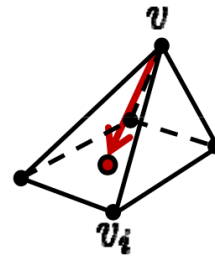
Smoothing with the Cotangent Laplacian



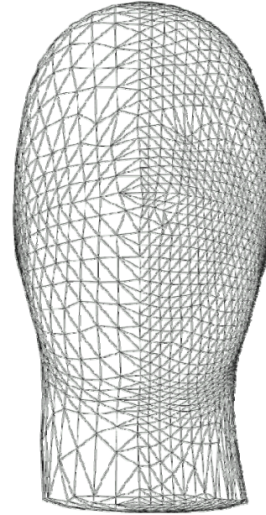
original



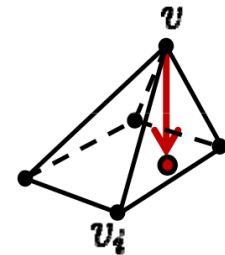
Uniform weights



normal
and
tangential
movement



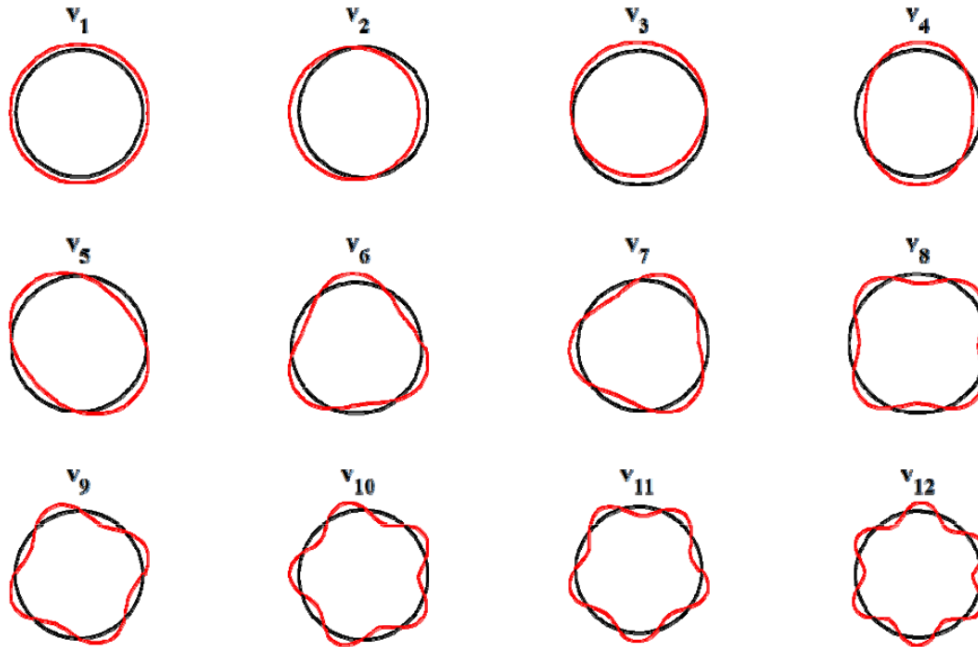
Cotangent weights



normal
movement

The Eigenvectors of L

$$\mathbf{L} = \mathbf{V} \mathbf{D} \mathbf{V}^T \quad \mathbf{V} = \begin{pmatrix} | & | & \dots & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \\ | & | & \dots & | \end{pmatrix}, \quad \mathbf{D} = \begin{pmatrix} k_1 & & & \\ & k_2 & & \\ & & \dots & \\ & & & k_n \end{pmatrix}$$



Spectral Analysis

- Cotangent Laplacian

$$\mathbf{L} = \mathbf{V}\mathbf{D}\mathbf{V}^T \quad \mathbf{V} = \begin{pmatrix} | & | & \dots & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \\ | & | & \dots & | \end{pmatrix}, \quad \mathbf{D} = \begin{pmatrix} k_1 & & & \\ & k_2 & & \\ & & \dots & \\ & & & k_n \end{pmatrix}$$



\mathbf{v}_2

\mathbf{v}_{50}

Demo

From Vallet et al., Eurographics 2008

Smoothing using the Laplacian Eigen-decomposition

$$\mathbf{P}^{smooth} = \mathbf{V}(\mathbf{D}_m)\mathbf{V}^T\mathbf{P} \quad , \quad \mathbf{D}_m = \begin{pmatrix} k_1 & & & & \\ & \dots & & & \\ & & k_m & & \\ & & & & 0 \end{pmatrix}$$

